

# An eightfold path to $E_8$

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## Introduction

Finite-dimensional real reflection groups were classified by Coxeter [2]. In two dimensions, they are the dihedral groups, and in higher dimensions there are three infinite series,  $A_n$ ,  $B_n$  and  $D_n$  in  $n$  dimensions (for each  $n > 2$ , although in fact  $A_3 = D_3$ ), and six exceptional cases,  $H_3$ ,  $H_4$ ,  $F_4$ ,  $E_6$ ,  $E_7$ ,  $E_8$ , where in each case the subscript indicates the dimension.

It is significant (I think) that the various finite series of reflection groups stop in dimensions 2, 4, and 8, precisely the dimensions of the complex numbers, quaternions, and octonions (Cayley numbers). Thus the ‘end of the road’ is reached for dihedral groups of order at least 12 in two dimensions,  $F_4$  and  $H_4$  in four dimensions, and  $E_8$  in eight dimensions.

This significance perhaps lies in the fact that reflections are not just geometric concepts, but (at least in 2, 4 or 8 dimensions) inescapably algebraic concepts. It is a well-known fact, which we teach to undergraduates, that reflections in 2 dimensions can be expressed in terms of complex numbers. Similarly, reflections in 4 dimensions can be expressed in terms of quaternions, and in 8 dimensions in terms of octonions. In each case the reflection which negates the unit vector  $r$  and fixes everything perpendicular to  $r$  is given by the rule

$$x \mapsto -r\bar{x}r.$$

This map is usually called *reflection in  $r$* .

The aim of this expository note is to bring many of these ideas together and to see how  $E_8$  may be reached by many different paths. In Section  $n$  we consider the case of dimension  $2^n$ . Thus we begin in Section 1 with a reminder of the description of dihedral groups in terms of complex numbers. Then in Section 2 we describe the 4-dimensional cases, first in terms of a real Euclidean space, then in terms of quaternions. Then in Section 3 we move on to  $E_8$ , in various manifestations as (a) 8-dimensional over  $\mathbb{R}$ , (b) 4-dimensional over  $\mathbb{C}$ , (c) 2-dimensional over  $\mathbb{H}$ , and (d) 1-dimensional over octonions.

## 1 Two dimensions

The 2-dimensional reflection groups are just the dihedral groups of order  $2k$ , consisting of  $k$  rotations about the origin, and  $k$  reflections in axes through the origin. Of particular interest are the cases  $k = 2$  and  $k = 3$ , which are treated in Subsections 1. $k$  below.

### 1.1 Complex numbers

Since the map  $z \mapsto \bar{z}$  maps  $i$  to  $-i$  while fixing 1, it is the map ‘reflect in the direction of  $\pm i$ ’. Similarly, ‘reflect in the direction of  $\pm 1$ ’ is expressed as  $z \mapsto -\bar{z}$ .

Moreover, if  $r$  is any complex number with  $|r| = 1$  (that is  $r\bar{r} = 1$ ), then the map  $z \mapsto rz$  is rotation about the origin, such that 1 maps to  $r$ . Therefore we can obtain the map ‘reflect in the direction of  $\pm r$ ’ as the composite of

1. rotate  $r$  to 1, by  $z \mapsto \bar{r}z$ ;
2. reflect in 1, by  $\bar{r}z \mapsto \overline{\bar{r}z} = \overline{\bar{r}}z$ ;
3. rotate 1 back to  $r$ , by  $\overline{\bar{r}}z \mapsto r\overline{\bar{r}}z$ .

Thus it is the map

$$z \mapsto -r\bar{z}r. \tag{1}$$

Since the complex numbers are commutative, this can be simplified to  $z \mapsto -r^2\bar{z}$ , but I prefer not to do this, because then the above calculation goes through unchanged in the quaternions and even in the octonions.

More generally, for any non-zero complex number  $r$ , reflection in the direction of  $\pm r$  can be expressed as the composite map

$$\begin{aligned} z &\mapsto r^{-1}z \\ &\mapsto \frac{r^{-1}z}{r^{-1}z} = \bar{z}\bar{r}^{-1} = \bar{z}r/(\bar{r}r) \\ &\mapsto r\bar{z}r/(\bar{r}r). \end{aligned} \tag{2}$$

Now the product of any two reflections is a rotation, since

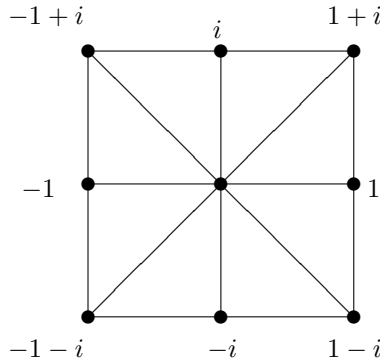
$$-s(-\bar{r}\bar{z}r)s = s\bar{r}z\bar{r}s = (\bar{r}s)^2z.$$

Moreover, the group structure on these rotations is given by multiplication in the complex numbers, since the composite of  $z \mapsto az$  with  $z \mapsto bz$  is  $z \mapsto (ab)z$ .

## 1.2 The dihedral group of order 8

In the general classification of reflection groups, the dihedral group of order 8 is denoted  $B_2$ . This is because it is the symmetry group of a square, which is the beginning of a series which includes the cube, hypercube and so on, whose reflection groups are  $B_3$ ,  $B_4$  and so on.

The four rotations of this dihedral group are given by multiplying by  $\pm 1$  or  $\pm i$ . Since reflection in  $-r$  is the same as reflection in  $r$ , reflecting in  $\pm 1$  or  $\pm i$  gives us only two reflections, and the other two are given by reflection in the two directions given by the unit vectors  $(\pm 1 \pm i)/\sqrt{2}$ . It is often convenient to avoid the factor of  $\sqrt{2}$  by using  $\pm 1 \pm i$  instead (see picture). Indeed, one could equally well use  $(\pm 1 \pm i)/2$ , in which case the picture would look slightly different.



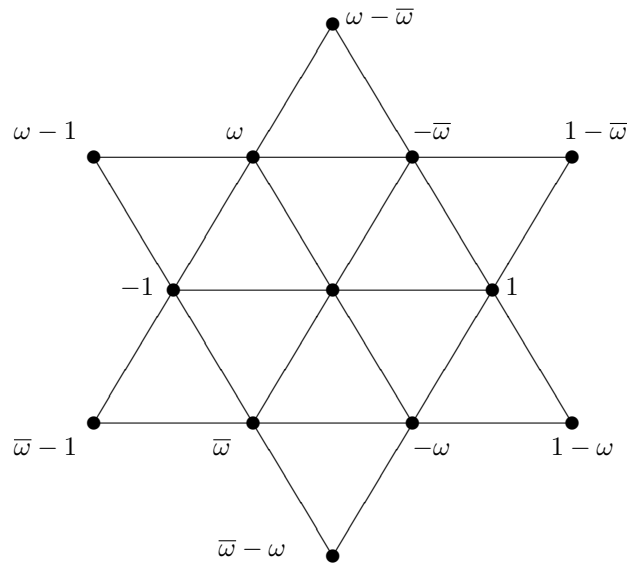
The reflecting vectors  $\pm 1, \pm i, \pm 1 \pm i$  are known as *roots*. For obvious reasons, the vectors  $\pm 1$  and  $\pm i$  are called *short roots* and  $\pm 1 \pm i$  are *long roots*. Notice that these roots lie in the ring of *Gaussian integers*,  $\mathbb{Z}[i]$ . Moreover, the long roots can be obtained from the short roots by multiplying by  $1 + i$ .

Converting from  $\mathbb{C}$  to  $\mathbb{R}^2$  in the usual way, we can write the short roots as the vectors  $(\pm 1, 0), (0, \pm 1)$  and the long roots as  $(\pm 1, \pm 1)$ . In the alternative picture, we can write the short roots as  $\pm 1 \pm i = (\pm 1, \pm 1)$ , and the long roots as  $\pm 2 = (\pm 2, 0)$  and  $\pm 2i = (0, \pm 2)$ .

### 1.3 The dihedral group of order 12

The dihedral group of order 12 also occupies a special place in the world of reflection groups. It is the symmetry group of a regular hexagon, and like squares and equilateral triangles, but unlike any other regular polygons, regular hexagons can tile the plane. This group is therefore given a special name,  $G_2$ .

Let  $\omega = (-1 + \sqrt{-3})/2$  be a primitive cube root of 1 in the complex numbers. Then the rotations of  $G_2$  are given by the powers of  $\pm\omega$ . Three of the six reflections are given by the same vectors, and the other three are given by  $\pm\omega^a\sqrt{-1}$ . As in the case of  $B_2$ , it is convenient to scale these to  $\pm\omega^a(\omega - \bar{\omega}) = \pm\omega\sqrt{-3}$ , or to  $\pm\omega^a(\omega - \bar{\omega})/3 = \pm\omega\sqrt{-1/3}$ . (See the picture.)



For completeness, let us note that there is a subgroup consisting of the three rotations by  $1, \omega, \bar{\omega}$  and the three reflections in  $\pm 1, \pm\omega, \pm\bar{\omega}$ . This is a dihedral group of order 6, and is known as  $A_2$ . In both cases  $A_2$  and  $G_2$ , the corresponding ring of complex integers is  $\mathbb{Z}[\omega]$ , often called the ring of *Eisenstein integers*.

## 2 Four dimensions

Even in three dimensions the situation is radically different from two dimensions. Instead of there being an infinite number of indecomposable reflection groups, there are only three, namely  $A_3$  (the group of the regular tetrahedron),  $B_3$  (the group of the cube or regular octahedron), and  $H_3$  (the group of the regular dodecahedron or

icosahedron). All three can be described in terms of quaternions, as subgroups of 4-dimensional groups  $A_4$ ,  $B_4$  and  $H_4$  respectively.

Altogether there are five indecomposable reflection groups in four dimensions, namely  $A_4$ ,  $B_4$ ,  $D_4$ ,  $F_4$ , and  $H_4$ . We shall see that  $F_4$  contains both  $B_4$  and  $D_4$ , while  $H_4$  contains  $A_4$  and  $D_4$ .

## 2.1 Quaternions

The non-commutative ring of (real) quaternions is  $\mathbb{H} = \mathbb{R}[i, j, k]$  where

$$\begin{aligned} i^2 = j^2 = k^2 &= -1, \\ ij = -ji &= k, \\ jk = -kj &= i, \\ ki = -ik &= j. \end{aligned} \tag{3}$$

If  $q = a + bi + cj + dk$  then we write

$$\bar{q} = a - bi - cj - dk,$$

and then it is straightforward to compute that  $\bar{q}q$  is equal to the square of the Euclidean length of  $q$ . In particular, if  $q \neq 0$  then  $q^{-1} = \bar{q}/(\bar{q}q)$ . Moreover, since  $(qr)^{-1} = r^{-1}q^{-1}$ , we also have  $\overline{qr} = \bar{r}\bar{q}$ .

Reflections in 4-dimensional Euclidean space can be expressed in terms of quaternion notation in just the same way as in the complex numbers, though taking extra care because of the non-commutativity. That is, reflection in 1 is the map

$$q \mapsto -\bar{q}$$

So if  $\bar{r}r = 1$  then reflection in  $r$  is the map

$$q \mapsto -r\bar{r}q = -r\bar{q}r.$$

In the 4-dimensional cases  $F_4$  and  $H_4$  suitable sets of reflecting vectors (not necessarily of norm 1) can be found inside respectively the Hurwitz integers and the icosians, which are well-known rings of quaternions that we describe below.

These 4-dimensional reflection groups may again be described by *root systems*, in which each *root* is one of the reflecting vectors, scaled appropriately.

## 2.2 Complex reflection groups

We shall also describe these root systems in terms of  $\mathbb{C}^2$ , a kind of ‘halfway house’ between the real and quaternionic descriptions. The real reflections then need a new interpretation in this context. Recall that reflection in the real vector  $r$  is the map

$$v \mapsto v - 2\frac{(v, r)}{(r, r)}r,$$

where  $(v, r)$  denotes the inner product  $\sum v_i r_i$  of the vectors  $v = (v_i)$  and  $r = (r_i)$ . (This map is linear, and fixes  $v$  if  $(v, r) = 0$ , and maps  $r$  to  $-r$ , so must be the required reflection.) Similarly if  $v$  and  $r$  are complex vectors, with inner product  $(v, r) = \sum_i v_i \bar{r}_i$ , then the map

$$v \mapsto v - 2\frac{(v, r)}{(r, r)}r$$

again fixes  $v$  if  $(v, r) = 0$ , and maps  $r$  to  $r$ . But this map is linear over  $\mathbb{C}$ , so negates a complex 1-space, that is a real 2-space, so is not a reflection in the real sense.

To recover the real reflection, we have to make the inner products real. We define a *real* inner product to be any convenient real multiple of the real part of the *complex* inner product. Thus

$$\begin{aligned} v &\mapsto v - 2 \frac{\Re(v, r)}{(r, r)} r \\ &= v - \frac{(v, r) + \overline{(v, r)}}{(r, r)} r \end{aligned} \tag{4}$$

This map still takes  $r$  to  $-r$ , but now takes  $ir$  to itself.

### 2.3 Integer quaternions, $B_4$ and $C_4$

The ‘obvious’ analogue in the quaternions of the Gaussian integers is the ring

$$\mathbb{Z}[i, j, k] = \{a + bi + cj + dk \mid a, b, c, d \in \mathbb{Z}\}.$$

The units of this ring are just the elements  $\pm 1, \pm i, \pm j, \pm k$ , which form the well-known quaternion group  $Q_8$ . This ring is invariant not only under reflections in these units (‘short roots’), but also under reflections in vectors of norm (i.e. squared length) 2, such as  $1 + i$ . In total there are 24 such ‘long roots’ (6 choices for which two of  $1, i, j, k$  to take, and 4 choices of signs). Together these 8 short roots and 24 long roots form the ‘root system’ of type  $B_4$ .

Converting to  $\mathbb{R}^4$  in the obvious way, these roots become vectors of shape  $(\pm 1, 0, 0, 0)$  and  $(\pm 1, \pm 1, 0, 0)$ , up to permutations of the coordinates. The corresponding reflection group is generated by the corresponding 4 reflections in short roots and 12 reflections in long roots. Reflection in a short root just changes the sign of one of the four coordinates, while reflection in a long root swaps two coordinates (with or without changing their signs), so the full group has shape  $2^4.S_4$ .

Just as in the case  $B_2$ , we can interchange the roles of long and short roots, by multiplying the short roots by 2. This time, however, the numbers of long and short roots are different, so we obtain a different sort of root system, even though the reflection group is still the same. This new root system is called  $C_4$ , and has 12 short roots of the shape  $(\pm 1, \pm 1, 0, 0)$  and 8 long roots of the shape  $(\pm 2, 0, 0, 0)$ .

Cutting down to three dimensions (the 3-space of pure imaginary quaternions is the most convenient one to take), we obtain a root system of type  $B_3$  in which the roots are 6 of shape  $(\pm 1, 0, 0)$  and 12 of shape  $(\pm 1, \pm 1, 0)$ . With respect to a natural coordinate system for the cube, the short roots are the midpoints of the six faces, and the long roots are the midpoints of the edges. Similarly the  $C_3$  root system can be described by saying that the long roots are the vertices of a regular octahedron, and the short roots are the midpoints of the edges.

### 2.4 Hurwitz quaternions, $D_4$ and $F_4$

If we multiply the short roots of  $B_4$  by  $1 + i$  (on either the left or the right) we get 8 of the 24 long roots, namely  $\pm 1 \pm i$  and  $\pm j \pm k$ . To get short roots corresponding to the other long roots of  $B_4$ , we would have to multiply by  $(1 - i)/2$ , and then we would obtain 16 roots such as

$$(1 + j)(1 - i)/2 = (1 - i + j + k)/2.$$

Indeed it does not matter whether we multiply on the left or the right, in either case we end up with all 16 roots  $(\pm 1 \pm i \pm j \pm k)/2$ . It is a remarkable fact that the resulting set of 24 short roots is closed under quaternion multiplication, and hence spans a ring known as the Hurwitz quaternions, which is still ‘integral’ in the sense that the norms of the elements are integers.

This ring may be obtained by adjoining a single element such as

$$\omega = \frac{1}{2}(-1 + i + j + k).$$

Since  $\omega$  is of the form  $\frac{1}{2}(-1 + \sqrt{-3})$ , we have  $\omega^2 = \bar{\omega} = -1 - \omega$  and  $\omega^3 = 1$ , and is easy to see that the product of  $\omega$  with any of  $i, j, k$  is another element with  $\pm\frac{1}{2}$  in each of the four coordinates. Hence the ring consists of all elements  $a + bi + cj + dk$  where either  $a, b, c, d \in \mathbb{Z}$  or

$$a - \frac{1}{2}, b - \frac{1}{2}, c - \frac{1}{2}, d - \frac{1}{2} \in \mathbb{Z}.$$

Thus in particular the unit elements (that is the elements with norm 1) are now  $\pm 1, \pm i, \pm j, \pm k$  together with  $\frac{1}{2}(\pm 1 \pm i \pm j \pm k)$ , making 24 in all. These units form a group variously known as  $2.A_4$  or  $SL_2(3)$  or the binary tetrahedral group.

It follows that the set of 48 roots we have constructed forms a root system, in the sense that it is closed under reflection in any one of the roots. It is called the root system of type  $F_4$ . The short roots are the 24 units just listed, and the 24 long roots are their multiples by  $1 + i$ , and are identical to the long roots of  $B_4$ . The 24 short roots on their own form what is known as the root system of type  $D_4$ . Similarly, the 24 long roots also form a root system of type  $D_4$ .

Converting to  $\mathbb{R}^4$  as before, the roots of  $D_4$  may be taken as all 24 vectors of shape  $(\pm 1, \pm 1, 0, 0)$ . Or, on a different scale, the 8 vectors of shape  $(\pm 2, 0, 0, 0)$  together with the 16 of shape  $(\pm 1, \pm 1, \pm 1, \pm 1)$ . The roots of  $F_4$  are of two different lengths, and consist of the two copies of  $D_4$  just mentioned. They can be scaled so that either of them gives the short roots and the other one gives the long roots. In terms of quaternions, multiplication by  $1 + i$  converts from one version to the other. To obtain  $B_4$ , take all of the long roots  $(\pm 1, \pm 1, 0, 0)$  of  $F_4$  and the eight short roots of shape  $(\pm 1, 0, 0, 0)$ . Similarly,  $C_4$  may be obtained from all the short roots of  $F_4$  and a suitable set of 8 long roots. For example in the other description of  $F_4$ , we may take the short roots to be of shape  $(\pm 1, \pm 1, 0, 0)$ , and the 8 long roots of  $C_4$  to be of shape  $(\pm 2, 0, 0, 0)$ . Multiplication by  $1 + i$  gives different descriptions of the root systems  $B_4$  and  $C_4$ .

The full reflection group of  $F_4$  has shape  $2.(A_4 \times A_4).2.2$  in which the central 2 is negation of the whole 4-space, modulo which the two copies of  $A_4$  are left- and right-multiplication by the units. Then the maps  $q \mapsto \frac{1}{2}(1 + i)q(1 + i)$  and  $q \mapsto \bar{q}$  extend this to the whole group.

There are also descriptions of all these roots systems in terms of 2-dimensional complex spaces. The system of type  $F_4$  can be described by taking the short roots to be 8 of shape  $(\pm 1 \pm i, 0)$  and 16 of shape  $(i^a, i^b)$ , and the long roots to be their multiples by  $1 + i$ . Similar descriptions of the other systems can be obtained from their embeddings in  $F_4$ .

Indeed,  $D_4$  and  $F_4$  also have nice descriptions over the Eisenstein integers. We take 6 roots  $\pm\omega^a(\omega - \bar{\omega}, 0)$  and 18 roots  $\pm(\omega^a, \omega^b\sqrt{2})$  to be the roots of  $D_4$ , that is the short roots of  $F_4$ . Then the long roots of  $F_4$  are the sums of pairs of short roots which are perpendicular in the real sense. These can be calculated to be the vectors obtained from the short roots by multiplying by  $\sqrt{2}$  and swapping the two coordinates, thus  $\pm(2\omega^a, \omega^b\sqrt{2})$ , and  $\sqrt{2}(0, \omega^a - \omega^b)$  with  $a \neq b$ . Then  $B_4$  may be obtained from  $F_4$  by taking all the long roots but only the 8 short roots  $\pm(\omega - \bar{\omega}, 0)$  and  $\pm(1, \omega^a\sqrt{2})$ . Similarly  $C_4$  is obtained by taking all the short roots but only the 8 long roots  $\pm\sqrt{2}(0, \omega - \bar{\omega})$  and  $\pm(2\omega^a, \sqrt{2})$ .

## 2.5 Icosians, $A_4$ and $H_4$

There is a similar description of the reflection group of type  $H_4$ , obtained by extending  $D_4$  in a different way. We can imagine the  $D_4$  root system by looking at

the quaternions  $(\pm i \pm j \pm k)/2$  which are added to  $\pm 1/2$  as the vertices of a unit cube. Since a cube can be inscribed in a regular dodecahedron, one might wonder what would happen if one used the extra vertices of the dodecahedron in the same way as those of the cube. Indeed, there are two such dodecahedra, and in one case the extra 12 vertices are  $(\pm \sigma i \pm \tau j)/2$  and its images under  $i \mapsto j \mapsto k \mapsto i$ , where  $\sigma = \frac{1}{2}(\sqrt{5} - 1)$  and  $\tau = \frac{1}{2}(1 + \sqrt{5})$ . In the other case, which we shall use,  $\sigma$  and  $\tau$  are interchanged.

Closing under reflections in the roots we quickly see that there are 120 roots, which are the 24 roots of  $D_4$  together with the images of  $(\pm 1 \pm \tau i \pm \sigma j)/2$  under even permutations of  $\{1, i, j, k\}$ . Again we find the remarkable fact that these 120 roots are closed under quaternion multiplication. They form the group of units of the so-called *icosian ring*

$$\mathbb{Z}[i, j, k, \frac{1}{2}(1 + i + j + k), \frac{1}{2}(1 + \tau i + \sigma j)].$$

This group of order 120 is a double cover of  $A_5$ , also known as  $SL_2(5)$  or the binary icosahedral group.

The full reflection group of type  $H_4$  has shape  $2.(A_5 \times A_5).2$  in which we see left- and right-multiplications by this group of units, together with the map  $q \mapsto \bar{q}$  again.

Translating back to  $\mathbb{R}^4$ , we see that the roots of  $H_4$  are the even permutations of  $(\pm 2, 0, 0, 0)$ ,  $(\pm 1, \pm 1, \pm 1, \pm 1)$ , and  $(0, \pm 1, \pm \sigma, \pm \tau)$ . Inside  $H_4$  there is a copy of  $A_4$  consisting of 20 roots

$$(\pm 2, 0, 0, 0), (0, \pm 2, 0, 0), \pm(\pm 1, \pm 1, 1, 1), \pm(\pm 1, 0, \tau, \sigma), \pm(0, \pm 1, \sigma, \tau).$$

### 3 Eight dimensions

There are innumerable ways to make  $E_8$ . The rest of this note is devoted to describing a few of these constructions in some detail.

In the 8-dimensional case  $E_8$ , we can similarly obtain a complete set of reflecting vectors inside the Dickson–Coxeter integral octonions inside  $\mathbb{O}$ .

#### 3.1 Real $E_8$

Probably the most common description of  $E_8$  is to take first the  $D_8$  roots which are all permutations of  $(\pm 1, \pm 1, 0, 0, 0, 0, 0, 0)$ , so there are 112 of them, and then adjoin 128 roots of the form  $\frac{1}{2}(\pm 1, \pm 1, \pm 1, \pm 1, \pm 1, \pm 1, \pm 1, \pm 1)$ . According to taste, one can either take the sign combinations in which there are an even number of  $-$  signs, or those with an odd number.

#### 3.2 A Gaussian version of $E_8$

One of the simplest constructions of  $E_8$  starts from the  $B_2$  root system, consisting of four long roots which are the corners of a square, and four short roots which are the mid-points of the edges. We take 16 roots  $(2r, 0, 0, 0)$  where  $r$  is a short root of  $B_2$ , and  $6.4.4 = 96$  roots  $(r_1, r_2, 0, 0)$  where  $r_i$  are long roots of  $B_2$ , and 128 roots  $(r_1, r_2, r_3, r_4)$  where the  $r_i$  are short roots of  $B_2$  and their sum lies in the lattice spanned by the long roots. (Alternatively, this construction can be twisted by taking the sum *not* to lie in this lattice).

The  $B_2$  lattice may be embedded in the complex numbers as the so-called *Gaussian integers*  $\mathbb{Z}[i]$ . This makes  $E_8$  into a 4-dimensional lattice over the Gaussian integers. It then consists of all vectors  $(x_1, x_2, x_3, x_4) \in \mathbb{Z}[i]^4$  which satisfy

- $x_s - x_t \in (1 + i)\mathbb{Z}[i]$ ;
- $\sum_{t=1}^4 x_t \in 2\mathbb{Z}[i]$ .

The 240 roots are the minimal norm vectors of the lattice. There is a symmetry group  $(2 \times 4^3)S_4$  generated by the diagonal matrix  $\text{diag}(i, i, 1, 1)$  and the coordinate permutations, under which the roots fall into three orbits, as follows:

- 16 roots of shape  $(2, 0, 0, 0)$ ;
- 96 roots of shape  $(1 + i, 1 + i, 0, 0)$ ;
- 128 roots of shape  $(1, 1, 1, 1)$ .

To make this into  $E_8$ , we simply define the Euclidean norm to be half of the Hermitian norm on the ambient complex vector space.

### 3.3 An Eisenstein version of $E_8$

In the complex numbers, take  $\omega = e^{2\pi i/3}$  and  $\theta = \omega - \bar{\omega} = \sqrt{-3}$ . Define a lattice by the following conditions on vectors  $(x_0, x_1, x_2, x_3)$ :

- $x_t \in \mathbb{Z}[\omega]$ ;
- $x_1 + x_2 + x_3 \in \theta\mathbb{Z}[\omega]$ ;
- $x_0 + x_1 - x_2 \in \theta\mathbb{Z}[\omega]$ .

Then we see a symmetry cycling  $(x_1, x_2, x_3)$ , and another cycling  $(x_0, x_1, -x_2)$ , which together generate a group  $2 \cdot A_4$  acting monomially on the four coordinates. Together with the diagonal element  $\text{diag}(\omega, 1, 1, 1)$  this generates a symmetry group  $3^4 : 2 \cdot A_4$ . The roots (vectors of minimal norm in the lattice) fall into two orbits under this monomial group, as follows:

- 24 roots of shape  $(\theta, 0, 0, 0)$ ;
- 216 roots of shape  $(0, 1, 1, 1)$ .

The Euclidean norm which makes this into  $E_8$  is  $2/3$  of the natural Hermitian norm.

The sublattice consisting of the vectors with  $x_0 = 0$  is a copy of the  $E_6$  lattice, and the sublattice of that which consists of vectors with  $x_2 = x_3$  is a copy of the  $F_4$  lattice.

### 3.4 A Hurwitz version of $E_8$

In this construction we take two copies of the  $F_4$  lattice (which is the same as the  $D_4$  lattice), identified with suitable scaled copies of the Hurwitz integral quaternions. In the quaternions, take the additive group generated by the  $D_4$  lattice as described above. This gives us the ring  $\mathbb{Z}[i, \omega]$  of *Hurwitz integral quaternions*. The units are the roots  $\pm 1, \pm i, \pm j, \pm k, \frac{1}{2}(\pm 1 \pm i \pm j \pm k)$  of  $D_4$ , and the elements of norm 2 are  $(1 + i)$  times these, that is  $\pm 1 \pm i, \pm 1 \pm j, \pm 1 \pm k, \pm i \pm j, \pm i \pm k, \pm j \pm k$ , which can be thought of as the long roots of  $F_4$ .

We now take 48 roots  $(2r, 0)$  where  $r$  is a short root of  $F_4$ , together with  $24 \times 8 = 192$  roots  $(r, qr)$  where  $r$  is a long root and  $q \in Q_8$ . If  $F_4$  is labelled so that  $\pm 1 \pm i$  are short and  $\pm 2$ , etc, are long, this gives

$(\pm 2, \pm 2, 0, 0 \mid 0, 0, 0, 0)$	48
$(\pm 2, 0, 0, 0 \mid \pm 2, 0, 0, 0)$	64
$(\pm 1, \pm 1, \pm 1, \pm 1 \mid \pm 1, \pm 1, \pm 1, \pm 1)$	128



where in the last case there must be an even number of minus signs. Clearly we now see more symmetry, fusing the first two orbits of roots. We could also twist this by changing sign on one coordinate, so that there is an odd number of minus signs instead.

If instead  $F_4$  is labelled so that  $\pm 1, \pm i$  etc are short, and  $\pm 1 \pm i$  etc are long, we get

$$\begin{array}{ll} (\pm 2, 0, 0, 0 \mid 0, 0, 0, 0) & 16 \\ (\pm 1, \pm 1, \pm 1, \pm 1 \mid 0, 0, 0, 0) & 32 \\ (\pm 1, \pm 1, 0, 0 \mid \pm 1, \pm 1, 0, 0) & 6.4.2.4 = 192 \end{array}$$

where in the last case the right hand pair of 1s can either be in the same positions as the left hand pair, or in the complementary positions. Labelling the coordinates  $\infty, 0, 1, 3, 2, 6, 4, 5$  in that order enables us to describe the supports of the vectors of shape  $(\pm 1^4, 0^4)$ : they are either  $\infty$  with a line  $t, t+1, t+3 \pmod{7}$  of the projective plane of order 2, or the complement thereof.

Now this construction of  $E_8$  can be described as taking all vectors  $(x, y)$  with  $x, y \in \mathbb{Z}[i, \omega]$  and  $x + y \in (1 + i)\mathbb{Z}[i, \omega]$ . In the left vector space  $\mathbb{H}^2$  (with scalar multiplication given by  $\lambda(x, y) = (\lambda x, \lambda y)$ ) there is now a monomial group of symmetries generated by right-multiplication by the diagonal matrices  $\text{diag}(\lambda, \mu)$  where  $\lambda, \mu \in Q_8$ , together with  $\text{diag}(\omega, \omega)$ , and the coordinate permutation of order 2.

The roots fall into two orbits under this group, as follows:

- 48 roots of shape  $(1 + i, 0)$ ;
- 192 roots of shape  $(1, 1)$ .

Alternatively, we may multiply by the scalar  $1 + i$  so that the roots become of shape  $(2, 0)$  and  $(1 + i, 1 + i)$ .

### 3.5 An octonion version of $E_8$

We can identify the pairs of quaternions in the previous section with octonions in various ways, to obtain various octonion constructions of  $E_8$ . If we identify  $i, j, k$  with the octonions  $i_0, i_1, i_3$  respectively, and then identify  $(1 + i, 0)$  with  $i_\infty = 1$  and  $(0, 1 + i)$  with  $i_2$  then we obtain

- 16 roots  $\pm i_t$  coming from  $(\pm 1 \pm i, 0), (\pm j \pm k, 0), (0, \pm 1 \pm i), (0, \pm j \pm k)$ ;
- 32 roots  $\frac{1}{2}(\pm 1 \pm i_0 \pm i_1 \pm i_3)$  and  $\frac{1}{2}(\pm i_2 \pm i_4 \pm i_5 \pm i_6)$  coming from the other roots which lie in just one coordinate;
- 64 similar roots with subscripts in one of the sets  $\{\infty, 0, 2, 6\}, \{1, 3, 4, 5\}, \{\infty, 0, 4, 5\}, \{1, 2, 3, 6\}$ , coming from the roots  $(x, y)$  with  $x, y \in Q_8$ .
- 64 roots with subscripts in one of  $\{\infty, 1, 2, 4\}, \{\infty, 1, 5, 6\}$  or their complements, coming from  $\omega(x, y)$ ;
- 64 roots with subscripts in one of  $\{\infty, 2, 3, 5\}, \{\infty, 3, 4, 6\}$  or the complement, coming from  $\bar{\omega}(x, y)$ .

Now (*pace* Kirmse) this set of roots  $r$  is not closed under octonion multiplication, but it turns out that the set  $\{(1 + i_0)r(1 + i_0)/2\}$  is closed under multiplication. It is known as the Dickson–Coxeter non-associative ring of integral octonions.

One way to obtain this multiplicatively closed version directly is to change the roots of the Hurwitz version of  $E_8$ , by replacing the diagonal symmetry  $\text{diag}(\omega, \omega)$  by  $\text{diag}(\omega, \bar{\omega})$ , so that the roots are the images under the new monomial group of  $(1 + i, 0)$  and  $(1, 1)$ . Or, in the scaled version, images of  $(2, 0)$  and  $(1 + i, 1 + i)$ .

### 3.6 An icosian construction of $E_8$

From  $H_4$ : define  $N : \mathbb{Q}[\sqrt{5}] \rightarrow \mathbb{Q}$  by  $N(a + b\sigma) = a$ , and define a new norm  $N(q\bar{q})$  on  $H_4$ . Now the things of norm 1 are the original things of norm 1, together with their multiples by  $\sigma$ . Thus we obtain 240 roots.

(If we apply this process to  $H_2$  we get  $A_4$ , and if we apply it to  $H_3$  we get  $D_6$ .)

### 3.7 Another complex version of $E_8$

Consider the ring  $\mathbb{Z}[\alpha]$  of complex numbers, where  $\alpha = \frac{1}{2}(-1 + \sqrt{-7})$ , so that  $\alpha^2 + \alpha + 2 = 0$ . Let  $\beta = \bar{\alpha}$ . We use a symmetry group  $2 \cdot A_4$  acting on vectors  $(x_0, x_1, x_2, x_3)$ , generated by  $(x_1, x_2, x_3)$  and  $(x_0, -x_1, x_2)$ . The 240 roots are then the images under this group of the following, where  $x, y, z \in \{\alpha, \beta\}$ :

- 8 roots of shape  $(\alpha - \beta, 0, 0, 0)$ ;
- 24 roots of shape  $(-xy, 1, 1, 1)$ ;
- 64 roots of shape  $(1, x, y, z)$ ;
- 144 roots of shape  $(0, 1, -x, yz)$ .

(Note that there is a sign error in the description of this lattice on page 10 of the Atlas of Finite Groups [1].)

The automorphism group of this lattice is a double cover  $2 \cdot A_7$  of the alternating group  $A_7$ . It may be generated by the monomial group  $2 \cdot A_4$  together with the matrix

$$\frac{1}{\alpha - \beta} \begin{pmatrix} \beta - \alpha & 0 & 0 & 0 \\ 0 & -\beta & \beta^2 & 1 \\ 0 & \beta^2 & 1 & -\alpha \\ 0 & 1 & -\alpha & 2 \end{pmatrix},$$

which has order 7 and is normalized by the element of order 3 which cycles the last three coordinates.

## References

- [1] J. H. Conway, R. T. Curtis, S. P. Norton, R. A. Parker and R. A. Wilson, *An ATLAS of Finite Groups*, Oxford University Press, 1985. Reprinted with corrections, December 2003.
- [2] H. S. M. Coxeter, Discrete groups generated by reflections, *Ann. Math.* **35** (1934), 588–621.